

## Fundamentals of Machine Learning: Part 2: Linear Classifiers

### Binary Classification Problem

**Dataset.** Consider a collection of features  $\mathbf{X} = \{X_1, \dots, X_d\}$ , such that  $\text{dom}(X_i) \subseteq \mathbb{R}$  for all  $i = 1 \dots d$ . These are our *independent variables*.

Consider also an additional variable  $Y$ , such that  $\text{dom}(Y) = \{0, 1\}$  or  $\text{dom}(Y) = \{-1, +1\}$ . This is our *binary dependent variable*.

Let  $X = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$  be a collection of *data points*, such that  $(\forall j \in 1 \dots n)(\mathbf{x}_j \in \mathbb{R}^d)$ . Let  $\mathbf{y} = \{y_1, \dots, y_n\}$  such that  $(\forall j \in 1 \dots n)(y_j \in \text{dom}(Y))$ . We write  $X$  as

$$\mathbf{X} = \begin{pmatrix} X_1 & X_2 & \dots & X_d \\ x_{11} & x_{12} & \dots & x_{1d} \\ x_{21} & x_{22} & \dots & x_{2d} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1} & x_{n2} & \dots & x_{nd} \end{pmatrix}$$

We also write  $\mathbf{x}_i = (x_{i1}, \dots, x_{id})$ .

The *binary classification problem* can be specified as follows:

Build a function  $f : \mathbb{R}^d \rightarrow \text{dom}(Y)$  that predicts the binary label of a data point  $\mathbf{x} \in \mathbb{R}^d$ .

**Dependent Variable.** In classification scenarios, the dependent variable  $Y$  is typically considered to be *categorical*. Many classification methods, in order to allow for the use of mathematical functions to represent classification decisions, assume that  $Y$  takes *numeric values*. For *binary classification problems*, some methods take advantage of treating values of  $Y$  as 0 and 1, while other methods (primarily those structured around *separating planes*) take advantage of treating values of  $Y$  as  $-1$  and  $+1$ . In what follows, we will treat levels of the dependent variable  $Y$  (i.e., the class labels) as whatever values that suit the best the method we are studying.

If  $\text{dom}(Y) = \{v_1, v_2\}$ , we sometimes use abbreviations  $\mathbf{X}_{v_1}$  and  $\mathbf{X}_{v_2}$  to represent all data points belonging to classes  $v_1$  and  $v_2$  respectively.

### LDA: Linear Discriminant Analysis

**Separation of classes.** For binary classification problems where the data points reside in the  $\mathbb{R}^d$  space (or a subspace of thereof), we often refer to solving the classification problem as in terms of *separating* the classes. Often, a mathematical (geometrical construct) like a plane, a hyperspace, or multidimensional surface are used as actual *separators* - with data points on one side of it classified into one (e.g., positive) class, and data points on the other side classified into the other (e.g., negative) class.

**Idea.** Consider our  $d$ -dimensional space  $\mathbb{R}^d$ . If we draw some line  $L(\mathbf{w}) : w_0 + w_1x_1 + \dots + w_dx_d = 0$  through this space, and *project* the data points  $\mathbf{X}$  on  $L(\mathbf{w})$ , then we can reduce the problem of separating data points in  $d$ -dimensional space to the problem of *finding the line equation  $L(\mathbf{w})$  that **best separates** the projections of the data points from  $\mathbf{X}$  along a 1-dimensional space*. (note, here  $\mathbf{w} = (w_0, w_1, \dots, w_d)$ )

Figures 1 and 2 demonstrate this idea. Figure 1 shows how the labeled data points from a dataset  $\mathbf{X}$  projected onto *some* line  $L(\mathbf{w})$ . Figure 2 shows just the one-dimensional picture - the projections of points from  $\mathbf{X}$  onto the line  $L(\mathbf{w})$ .

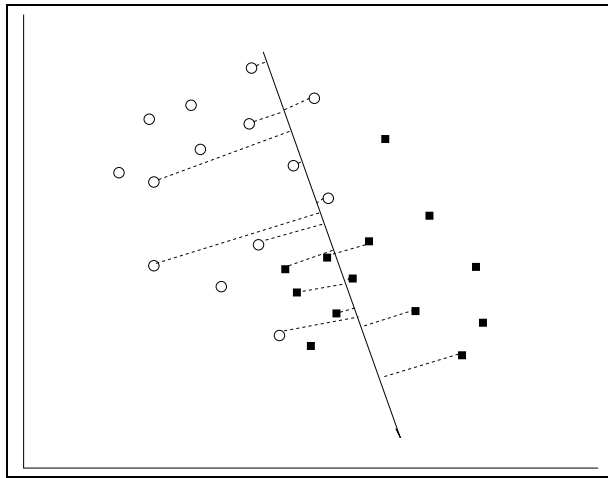


Figure 1: Linear Discriminant Analysis: projections of data points onto a single line.

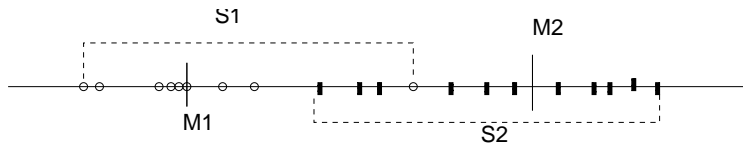


Figure 2: Linear Discriminant Analysis: separation of classes along a single line.

**Goal.** Following the idea expressed above, we want to *find the set of values*  $\mathbf{w} = (w_0, w_1, \dots, w_d)$  *such that the line*  $L(\mathbf{w})$  *is the best separating line for the training data*  $\langle \mathbf{X}, Y \rangle$ .

**Model Shape.** From the above, it is clear that we are looking for a model that is essentially an equation of a line in a  $d$ -dimensional space. The model is our line equation

$$L(\mathbf{w}) : w_0 + w_1x_1 + w_2x_2 + \dots + w_dx_d = 0$$

**Cost function/Optimization Criterion.** What is the right mathematical criterion that matches the intuition of "best separation" for the two classes along a line based on projections of the data points on this line?

We start our derivation by constructing the set  $A_{\mathbf{w}}$  of projections of points from  $\mathbf{X}$  onto  $L(\mathbf{w})$ . Specifically, without loss of generality, let us assume that  $\mathbf{w}$  is a *unit vector*, i.e.,

$$\mathbf{w}^T \mathbf{w} = 1$$

The projection of a data point ( $d$ -dimensional vector)  $\mathbf{x} = (x_1, \dots, x_d)$  onto  $\mathbf{w}$  is

$$\frac{\mathbf{w}^T \mathbf{x}}{\mathbf{w}^T \mathbf{w}} \mathbf{w} = (\mathbf{w}^T \mathbf{x}) \mathbf{w}$$

The value  $a = \mathbf{w}^T \mathbf{x}$  is the numeric offset of the projection of  $\mathbf{x}$  onto  $\mathbf{w}$ . The set  $A_{\mathbf{w}}$  is then defined as

$$A = \{\mathbf{w}^T \mathbf{x} | \mathbf{x} \in \mathbf{X}\} = \{a_1, \dots, a_n\}$$

Let us split  $A$  into  $A_0 = \{a_i | y_i = 0\}$  and  $A_1 = \{a_i | y_i = 1\}$ .

We can find the *means* of the sets  $A_0$  and  $A_1$ :

$$m_0 = \frac{1}{|A_0|} \sum_{a_i \in A_0} a_i = \frac{1}{|A_0|} \sum_{\mathbf{x}_i \in \mathbf{X}_0} \mathbf{w}^T \mathbf{x}_i = \frac{1}{|\mathbf{X}_0|} \mathbf{w}^T \sum_{\mathbf{x}_i \in \mathbf{X}_0} \mathbf{x}_i = \mathbf{w}^T \mu_0,$$

where  $\mu_0$  is the centroid of class 0 (set  $\mathbf{X}_0$ ).

Similarly, if we set  $\mu_1 = \frac{1}{|\mathbf{X}_1|} \sum_{\mathbf{x}_i \in \mathbf{X}_1} \mathbf{x}_i$ , then the mean point for class 1 along the line  $\mathbf{w}$  is found as:

$$m_1 = \mathbf{w}^T \mu_1$$

**Attempt 1 at cost function.** What if we set

$$f(w) = |m_0 - m_1| = \mathbf{w}^T (\mu_0 - \mu_1) \longrightarrow \max$$

as our cost function? This is a good idea but it needs to be upgraded, because it is possible that the means of the two classes are far apart, but the points are widely distributed (have a high variance). So, the real cost function needs to take variance into account.

**Attempt 2 at cost function.** Let

$$s_0^2 = \sum_{a_i \in A_0} (a_i - m_0)^2$$

$$s_1^2 = \sum_{a_i \in A_1} (a_i - m_1)^2$$

We call  $s_0$  and  $s_1$  the *scatter* of classes 0 and 1 respectively. Scatter is the *total squared deviation* of all data points in the class.

We want  $|m_0 - m_1|$  to be large, while we also want  $s_0$  and  $s_1$  to be small. One cost function that achieves this effect is the **Fisher Linear Discriminant Analysis (LDA) objective**:

$$J(\mathbf{w}) = \frac{(m_0 - m_1)^2}{s_0^2 + s_1^2} \longrightarrow \max$$

We call the vector  $\mathbf{w}$  that optimizes  $J(\mathbf{w})$  the *optimal linear discriminant*.

**Closed form solution?** Let us try to optimize  $J(\mathbf{w})$ .

First, let's consider the  $(m_0 - m_1)^2$  term.

$$(m_0 - m_1)^2 = (\mathbf{w}^T (\mu_0 - \mu_1))^2 = \mathbf{w}^T ((\mu_0 - \mu_1)(\mu_0 - \mu_1)^T) \mathbf{w}$$

In this expression,  $(\mu_0 - \mu_1)(\mu_0 - \mu_1)^T$  is a  $d \times d$  rank-one matrix.

Setting  $\mathbf{B} = (\mu_0 - \mu_1)(\mu_0 - \mu_1)^T$ , we arrive to

$$(m_0 - m_1)^2 = \mathbf{w}^T \mathbf{B} \mathbf{w}$$

Next, let us figure out the scatter:

$$s_0^2 = \sum_{a_i \in A_0} (a_i - m_0)^2 = \sum_{\mathbf{x}_i \in \mathbf{X}_0} (\mathbf{w}^T \mathbf{x}_i - \mathbf{w}^T \mu_0)^2 = \sum_{\mathbf{x}_i \in \mathbf{X}_0} (\mathbf{w}^T (\mathbf{x}_i - \mu_0))^2 = \mathbf{w}^T \left( \sum_{\mathbf{x}_i \in \mathbf{X}_0} (\mathbf{x}_i - \mu_0)(\mathbf{x}_i - \mu_0)^T \right) \mathbf{w}$$

Here,  $\sum_{\mathbf{x}_i \in \mathbf{X}_0} (\mathbf{x}_i - \mu_0)(\mathbf{x}_i - \mu_0)^T$  is also a  $d \times d$  rank-one matrix we call *scatter matrix for class 0*. Let's set  $\mathbf{S}_0 = \sum_{\mathbf{x}_i \in \mathbf{X}_0} (\mathbf{x}_i - \mu_0)(\mathbf{x}_i - \mu_0)^T$ .

Similarly, we can set  $\mathbf{S}_1 = \sum_{\mathbf{x}_i \in \mathbf{X}_1} (\mathbf{x}_i - \mu_1)(\mathbf{x}_i - \mu_1)^T$ . Setting

$$\mathbf{S} = \mathbf{S}_0 + \mathbf{S}_1,$$

we get

$$s_0^2 + s_1^2 = \mathbf{w}^T \mathbf{S}_0 \mathbf{w} + \mathbf{w}^T \mathbf{S}_1 \mathbf{w} = \mathbf{w}^T (\mathbf{S}_0 + \mathbf{S}_1) \mathbf{w} = \mathbf{w}^T \mathbf{S} \mathbf{w}$$

Thus,

$$J(\mathbf{w}) = \frac{\mathbf{w}^T \mathbf{B} \mathbf{w}}{\mathbf{w}^T \mathbf{S} \mathbf{w}}.$$

**Optimization.** Now, let's set

$$\frac{d}{d\mathbf{w}} J(\mathbf{w}) = 0$$

$$\frac{d}{d\mathbf{w}} J(\mathbf{w}) = \frac{2\mathbf{B}\mathbf{w}(\mathbf{w}^T \mathbf{S} \mathbf{w}) - 2\mathbf{S}\mathbf{w}(\mathbf{w}^T \mathbf{B} \mathbf{w})}{(\mathbf{w}^T \mathbf{S} \mathbf{w})^2} = 0$$

From here:

$$\mathbf{B}\mathbf{w}(\mathbf{w}^T \mathbf{S} \mathbf{w}) - \mathbf{S}\mathbf{w}(\mathbf{w}^T \mathbf{B} \mathbf{w}) = 0$$

or

$$\mathbf{B}\mathbf{w}(\mathbf{w}^T \mathbf{S} \mathbf{w}) = \mathbf{S}\mathbf{w}(\mathbf{w}^T \mathbf{B} \mathbf{w})$$

Following this:

$$\mathbf{B}\mathbf{w} = \mathbf{S}\mathbf{w} \frac{\mathbf{w}^T \mathbf{B} \mathbf{w}}{\mathbf{w}^T \mathbf{S} \mathbf{w}}$$

$$\mathbf{B}\mathbf{w} = J(\mathbf{w})\mathbf{S}\mathbf{w} = \lambda\mathbf{S}\mathbf{w},$$

where  $\lambda = J(\mathbf{w})$ .

This leads to:

$$(\mathbf{S}^{-1}\mathbf{B})\mathbf{w} = \lambda\mathbf{w},$$

that is:

*The set of parameters  $\mathbf{w}$  that optimizes the Fisher LDA objective is the eigenvector of the matrix  $\mathbf{S}^{-1}\mathbf{B}$  that corresponds to the largest eigenvalue  $\lambda$  of this matrix.*

For a two-class problem with a non-singular matrix  $\mathbf{S}$  (i.e.,  $\mathbf{S}^{-1}$  exists), the solution can be obtained as

$$\hat{\mathbf{w}} = \mathbf{S}^{-1}(\mu_0 - \mu_1)$$

with  $\mathbf{w}$  being  $\hat{\mathbf{w}}$  normalized.