## Machine Learning: <br> Support Vector Machines: Linear Kernel, Dual Problem

## Soft Margin SVMs (reprise): Linear and Non-Separable

## Cases

Recall the definition of the soft margin Support Vector Machine.
Let $(X, Y), X=\left\{\mathbf{x}_{1}, \ldots, \mathbf{x}_{m}\right\}, Y=\left\{y_{1}, \ldots, y_{m}\right\}, \mathbf{x}_{i} \in \mathbb{R}^{n}, y_{i} \in\{-1,+1\}$ be the training set.

Let $\mathbf{w}=\left(w_{1}, \ldots, w_{n}\right)$, and $b$ be the linear coefficients and the intercept for a function

$$
L(\mathbf{w}, b)=\mathbf{x}^{T} \mathbf{w}+b
$$

The soft margin Support Vector Machine optimization problem is described below:

## Objective Function:

$$
J(\mathbf{w}, b)=\min _{\mathbf{w}, b,\left\{\xi_{i}\right\}}\left(\frac{\|\mathbf{w}\|^{2}}{2}+C \sum_{i=1}^{n} \xi_{i}\right)
$$

## Subject to constraints:

$$
Q_{1}: y_{i}\left(\mathbf{w} \cdot \bar{x}_{i}+b\right) \geq 1-\xi_{i}, \forall \bar{x}_{i} \in X
$$

## Training SVM Classifiers

Step 1. Get rid of the intercept. This can be accomplished by replacing all vectors $\bar{x}=\left(a_{1}, \ldots, a_{d}\right) \in X$ with the vectors $\overline{x^{\prime}}=\left(a_{1}, \ldots, a_{d}, 1\right)$, and replacing the vector of weights $\mathbf{w}=\left(w_{1}, \ldots, w_{d}\right)$ with the vector $\mathbf{w}^{\prime}=\left(w_{1}, \ldots, w_{d}, b\right)$. (This is a standard procedure that we have seen multiple times already).

Without loss of generality, we assume that all vectors $\mathbf{w}$ and $\bar{x}$ mentioned below have gone through this transformation.

Step 2. Pick the problem to optimize. There are two SVM problems that can be solved: primal and dual.

We address the solution of the dual problem here.

Step 3. Introduce Lagrangian Multipliers. One approach to optimizing a function $f(\mathbf{x})$ subject to some constraints $Q_{1}, \ldots, Q_{k}$ of the form $Q_{i}: g_{i}(\mathbf{x}) \geq 0$ is to consider optmizing a function

$$
L(\alpha)=f(\mathbf{x})+\sum_{i=1}^{k} \alpha_{k} g_{i}(\mathbf{x})
$$

Here, the values $\alpha_{i}$ are called Lagrangian multipliers and can be thought of as the penalties assessed for the value $\mathbf{x}$ not satisfying the constraints $g_{i}(\mathbf{x})$.

Essentially, $\alpha_{1}, \ldots, \alpha_{k}$ make it difficult for $L()$ to reach its optimal value at a point $\mathbf{x}$ where constraints $g_{1}(\mathbf{x}), \ldots, g_{k}(\mathbf{x})$ are violated.

We apply this approach to the problem of optimizing the soft margin SVM function as follows.

We replace the problem of optimizing $J(\mathbf{w}, b)$ subject to constraints $Q_{1}, \ldots, Q_{m}$ with the problem of optimizing the Lagrangian function:

$$
L=\frac{\|\mathbf{w}\|^{2}}{2}+C \sum_{i=1}^{m} \xi_{i}-\sum_{i=1}^{m} \alpha_{i}\left(y_{i}\left(\mathbf{w} \cdot \mathbf{x}_{i}+b\right)-1+\xi_{i}\right)-\sum_{i=1}^{m} \beta_{i} \xi_{i}
$$

where $\alpha_{1}, \ldots, \alpha_{m}$ are Lagrangian multipliers applied to the constraints $y_{i}(\mathbf{w} \cdot$ $\left.\mathbf{x}_{i}+b\right)-1+\xi_{i} \geq 0$, and $\beta_{1}, \ldots, \beta_{m}$ are Lagrangian multipliers applied to the constraints $\xi_{i} \geq 0$.

When $L$ is considered as a function of $\mathbf{w}, b$, and $\xi, L$ reaches its optimal value at the point where

$$
\begin{gathered}
\frac{\partial L}{\partial \mathbf{w}}=\mathbf{w}-\sum_{i=1}^{m} \alpha_{i} y_{i} \mathbf{x}_{\mathbf{i}}=0, \\
\frac{\partial L}{\partial b}=-\sum_{i=1}^{n} \alpha_{i} y_{i}=0, \\
\frac{\partial L}{\partial \xi_{i}}=C-\alpha_{i}-\beta_{i}=0 .
\end{gathered}
$$

From these equations, we obtain:

$$
\mathbf{w}=\sum_{i=1}^{m} \alpha_{i} y_{i} \mathbf{x}_{\mathbf{i}}
$$

and

$$
\beta_{i}=C-\alpha_{i}
$$

Noticing that $\alpha_{i} \neq 0$ implies that $\mathbf{x}_{\mathbf{i}}$ is a support vector, the first equality can be interpreted as

The vector $\mathbf{w}$ defining the separating plane (i.e., the normal vector to the plane) is determined as a linear combination of the support vectors for the plane.

Under the assumption that we reached the optimum values of $\mathbf{w}, b$ and $\xi_{1}, \ldots, \xi_{m}$, we can eliminate these from the Lagrangian function $L$ and construct a dual function:

$$
\begin{gathered}
L_{\text {dual }}=\frac{\mathbf{w}^{T} \mathbf{w}}{2}-\mathbf{w}^{T} \sum_{i=1}^{m} \alpha_{i} y_{i} \mathbf{x}_{\mathbf{i}}+\sum_{i=1}^{n} \alpha_{i} y_{i} b-\sum_{i=1}^{m} \alpha_{i}+\sum_{i=1}^{m}\left(C-\alpha_{i}-\beta_{i}\right) \xi_{i}= \\
=\sum_{i=1}^{n} \alpha_{i}-\frac{1}{2} \mathbf{w}^{T} \mathbf{w}=\sum_{i=1}^{n} \alpha_{i}-\frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \alpha_{i} \alpha_{j} y_{i} y_{j} \mathbf{x}_{\mathbf{i}} \mathbf{x}_{\mathbf{j}}
\end{gathered}
$$

i.e.,

$$
L_{d u a l}=\sum_{i=1}^{n} \alpha_{i}-\frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \alpha_{i} \alpha_{j} y_{i} y_{j} \mathbf{x}_{\mathbf{i}}^{T} \mathbf{x}_{\mathbf{j}}
$$

We need to maximize $L_{\text {dual }}$ subject to the following constraints:
$0 \leq \alpha_{i} \leq C$ (because $C-\alpha_{i}=\beta_{i} \geq 0$ ) and

$$
\sum_{i=1}^{m} \alpha_{i} y_{i}=0
$$

Step 4. Gradient Ascent/Stochastic Gradient Ascent. Our goal is to maximize

$$
L_{d u a l}(\alpha)=J(\alpha)=\sum_{i=1}^{n} \alpha_{i}-\frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \alpha_{i} \alpha_{j} y_{i} y_{j} \mathbf{x}_{\mathbf{i}}^{T} \mathbf{x}_{\mathbf{j}}
$$

subject to

$$
\begin{gathered}
0 \leq \alpha_{i} \leq C \\
\sum_{i=1}^{m} \alpha_{i} y_{i}=0
\end{gathered}
$$

Given $\alpha_{i}$, the part of $J($ alpha $)$ that depends on $\alpha_{i}$ can be written as follows:

$$
J\left(\alpha_{i}\right)=\alpha_{i}-\frac{1}{2} \alpha_{i}^{2} \mathbf{x}_{\mathbf{i}}^{T} \mathbf{x}_{\mathbf{i}}-\frac{1}{2} \alpha_{i} y_{i} \sum_{j=1, j \neq i} \alpha_{j} y_{j} \mathbf{x}_{\mathbf{i}}^{T} \mathbf{x}_{\mathbf{j}}
$$

The gradient of $J(\alpha)$ is

$$
\nabla J(\alpha)=\left(\frac{\partial J}{\partial \alpha_{1}}, \ldots, \frac{\partial J}{\partial \alpha_{m}}\right)
$$

where

$$
\frac{\partial J}{\partial \alpha_{i}}=1-y_{i}\left(\sum_{j=1} m \alpha_{j} y_{j} \mathbf{x}_{\mathbf{i}}^{T} \mathbf{x}_{\mathbf{j}}\right)
$$

Gradient Ascent. The gradient ascent method proceeds as follows:

- $\alpha_{0}=(0,0, \ldots, 0)$ (or some other chosen set of initial values)
- $\alpha_{t+1}=\alpha_{\mathbf{t}}+\eta_{t} \nabla J\left(\alpha_{\mathbf{t}}\right)$

Stochastic Gradient Ascent. Note that $\alpha_{i}$ coefficients represent to the impact of individual training set data points on the final shape of the function. These can be considered separately.

The update rule for the stochastic gradiaent ascent is

$$
\alpha_{i}^{t+1}=\alpha_{i}^{t}+\eta_{i}\left(1-y_{k} \sum_{j=1}^{m} \alpha_{j}^{t} y_{j} \mathbf{x}_{\mathbf{i}}^{T} \mathbf{x}_{\mathbf{j}}\right)
$$

## References

[1] Mohammed J. Zaki, Wagner Meira Jr., Data Mining and Analysis: Fundamental Concepts and Algorithms, Cambridge University Press, 2014.

