

CSC 480: Artificial Intelligence

Wumpus World Lab

Dr. Franz J. Kurfess
Computer Science Department
Cal Poly

Hexagonal Wumpus World

- ◆ similar to the grid wumpus world, but the underlying geometry is hexagonal
- ◆ mark the status of tiles
 - ◆ visited (V)
 - ◆ safe (OK)
 - ◆ possible pit (P?)
 - ◆ confirmed pit (P!)
 - ◆ possible wumpus (W?)
 - ◆ confirmed wumpus (W!)
 - ◆ percepts (SBGPC)
 - ◆ orientation of the agent
 - ◆ action (arrow or line)

Task Definition

- ◆ add information about the stench and breeze percepts in this map by coloring or shading the respective tiles
 - ◆ percepts are only available for the current location
 - ◆ the agent knows about the existence of adjacent tiles, but can't perceive anything about adjacent tiles
- ◆ use a clockwise search strategy
 - ◆ the agent starts from its current orientation and examines adjacent tiles in a clockwise direction
 - ◆ if it finds a safe, unvisited place, it proceeds there, and puts the unexamined adjacent tiles on the fringe
 - ◆ if there aren't any safe unvisited ones, it continues with unexplored tiles from its fringe
 - ◆ the fringe may be re-arranged so that adjacent tiles are explored first to minimize movement in this online search
 - ◆ if only risky locations are left, it takes the first one clockwise
- ◆ keep track of the activities of your agent through the template below
 - ◆ create copies of it as needed (e.g. for each step)

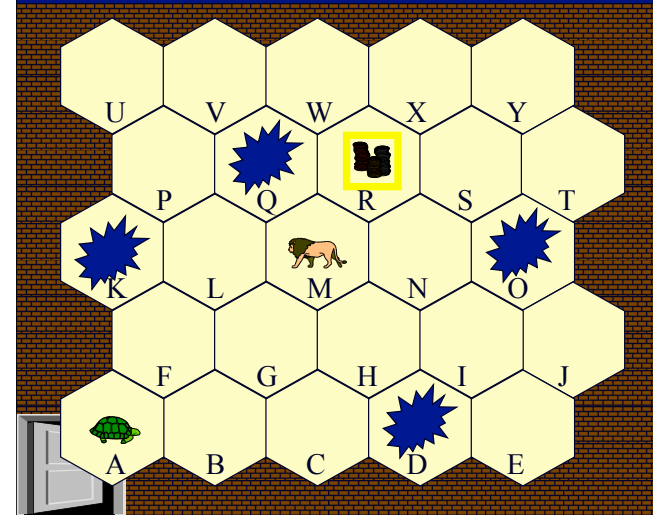
Knowledge and Reasoning

- ◆ accumulate knowledge your agent has about the Wumpus world
 - ◆ current location and percept
 - ◆ new knowledge from observation (percepts)
 - ◆ new knowledge from reasoning
 - ◆ definitive locations of pits, wumpus
 - ◆ speculation
 - ◆ possible locations for pit, wumpus
 - ◆ probabilities (optional)
 - ◆ determine the next action

Alternative Mode: WW Game

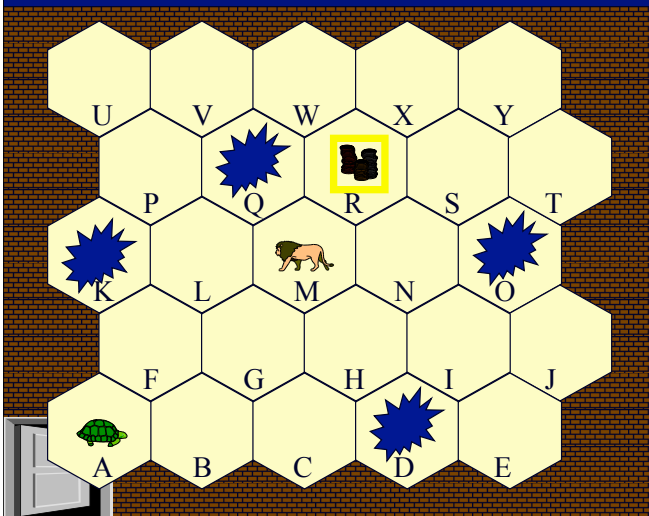
- ♦ if you want to make this more realistic, you can do it as a game:
 - ♦ one person (A) sets up the environment with locations for the wumpus and pits
 - ♦ the other person (B), who should not know or see that setup, traverses the Wumpus World by asking A about properties of the current tile
 - ♦ A responds with the percept for that location
 - ♦ B updates its world model on the template, and decides what the next action will be

Hex WW Configuration F10



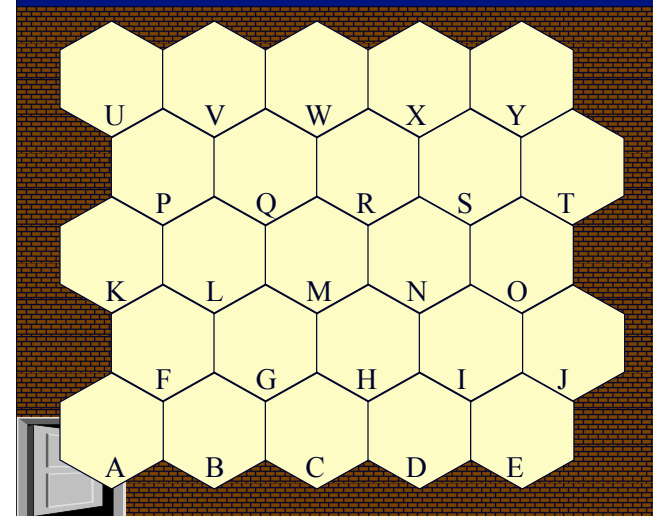
- ♦ add information about the stench and breeze percepts in this map by coloring or shading the respective tiles

Hex WW Breeze + Smell



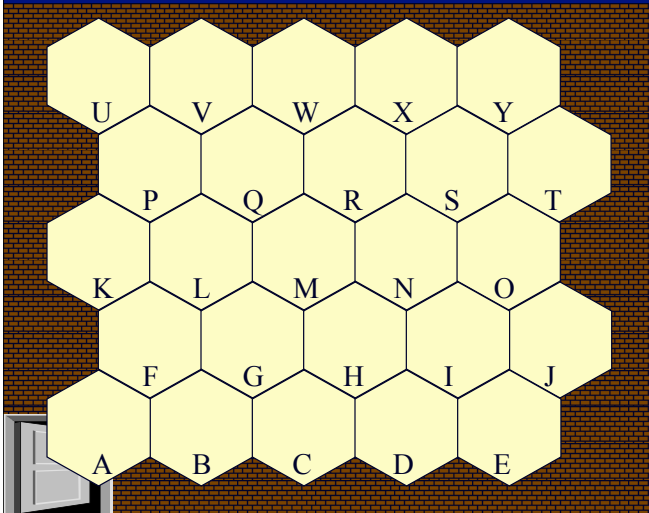
- ♦ add information about the stench and breeze percepts in this map by coloring or shading the respective tiles

Hex WW: Legend



- safe location: OK 😊
- visited location: V 🐢
- possible pit: P? 😟
- confirmed pit: P! 😞
- possible wumpus: W? 😟
- confirmed wumpus: W! 😞
- shoot arrow: 🏹
- return path: ←

Hex WW: Template

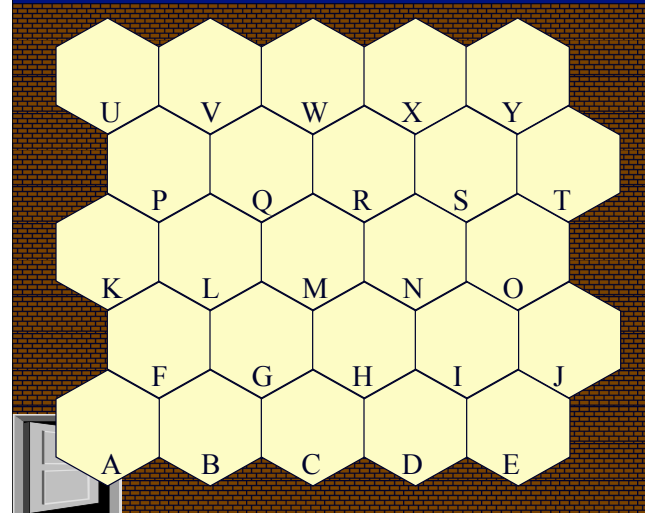


- ♦ Agent Position
e.g. A
- ♦ Percept
[SBGPC]
- ♦ New Knowledge
 - ♦ observation
percepts for
current square
 - ♦ reasoning
adjacent squares
ok?
 - ♦ speculative
possible
locations for pits,
wumpus
- ♦ Next Action
 - ♦ move
 - ♦ turn left (60
degrees)
 - ♦ turn right (60
degrees)
 - ♦ shoot
 - ♦ grab
 - ♦ exit

© 2004-10 Franz Kurfess

Lab Exercise Reasoning

Hex WW: Template

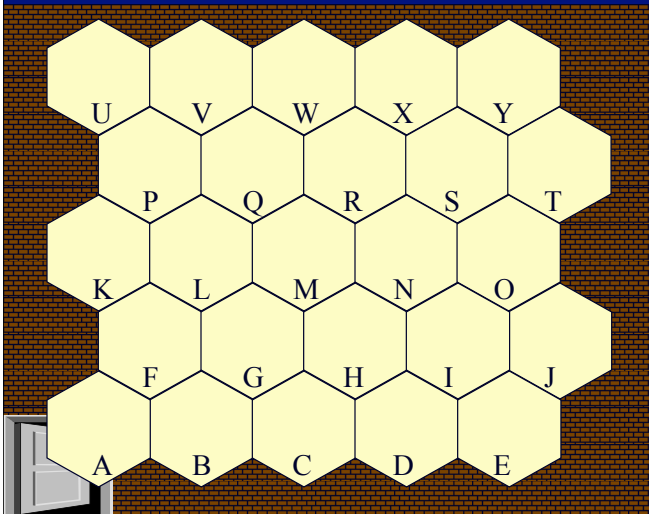


- ♦ Agent Position
e.g. A
- ♦ Percept
[SBGPC]
- ♦ New Knowledge
 - ♦ observation
percepts for
current square
 - ♦ reasoning
adjacent squares
ok?
 - ♦ speculative
possible
locations for pits,
wumpus
- ♦ Next Action
 - ♦ move
 - ♦ turn left (60
degrees)
 - ♦ turn right (60
degrees)
 - ♦ shoot
 - ♦ grab
 - ♦ exit

© 2004-10 Franz Kurfess

Lab Exercise Reasoning

Hex WW: Template

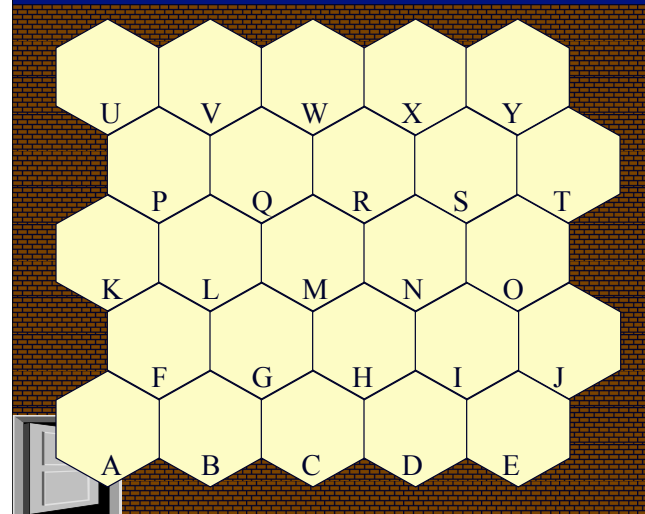


- ♦ Agent Position
e.g. A
- ♦ Percept
[SBGPC]
- ♦ New Knowledge
 - ♦ observation
percepts for
current square
 - ♦ reasoning
adjacent squares
ok?
 - ♦ speculative
possible
locations for pits,
wumpus
- ♦ Next Action
 - ♦ move
 - ♦ turn left (60
degrees)
 - ♦ turn right (60
degrees)
 - ♦ shoot
 - ♦ grab
 - ♦ exit

© 2004-10 Franz Kurfess

Lab Exercise Reasoning

Hex WW: Template

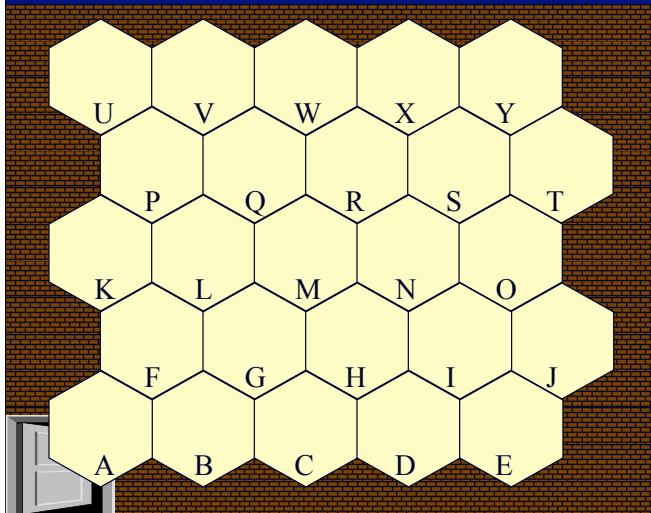


- ♦ Agent Position
e.g. A
- ♦ Percept
[SBGPC]
- ♦ New Knowledge
 - ♦ observation
percepts for
current square
 - ♦ reasoning
adjacent squares
ok?
 - ♦ speculative
possible
locations for pits,
wumpus
- ♦ Next Action
 - ♦ move
 - ♦ turn left (60
degrees)
 - ♦ turn right (60
degrees)
 - ♦ shoot
 - ♦ grab
 - ♦ exit

© 2004-10 Franz Kurfess

Lab Exercise Reasoning

Hex WW: Template

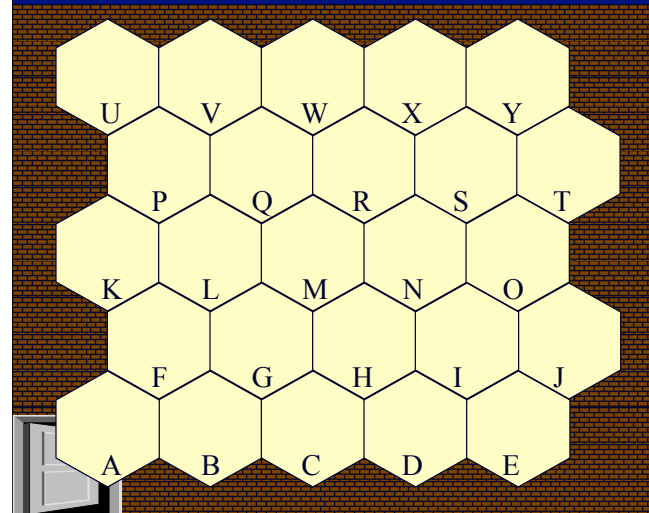


- ♦ Agent Position
e.g. A
- ♦ Percept
[S B G P C]
- ♦ New Knowledge
 - ♦ observation
percepts for
current square
 - ♦ reasoning
adjacent squares
ok?
 - ♦ speculative
possible
locations for pits,
wumpus
- ♦ Next Action
 - ♦ move
 - ♦ turn left (60
degrees)
 - ♦ turn right (60
degrees)
 - ♦ shoot
 - ♦ grab
 - ♦ exit

© 2004-10 Franz Kurtesz

Lab Exercise Reasoning

Hex WW: Template

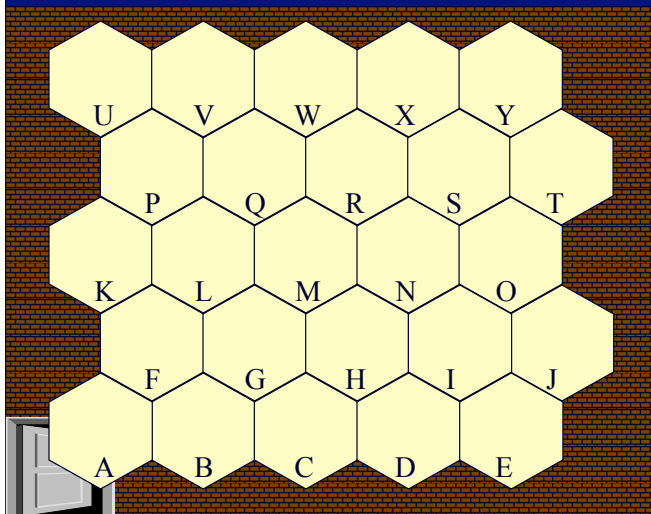


- ♦ Agent Position
e.g. A
- ♦ Percept
[S B G P C]
- ♦ New Knowledge
 - ♦ observation
percepts for
current square
 - ♦ reasoning
adjacent squares
ok?
 - ♦ speculative
possible
locations for pits,
wumpus
- ♦ Next Action
 - ♦ move
 - ♦ turn left (60
degrees)
 - ♦ turn right (60
degrees)
 - ♦ shoot
 - ♦ grab
 - ♦ exit

© 2004-10 Franz Kurtesz

Lab Exercise Reasoning

Hex WW: Template



- ♦ Agent Position
e.g. A
- ♦ Percept
[S B G P C]
- ♦ New Knowledge
 - ♦ observation
percepts for
current square
 - ♦ reasoning
adjacent squares
ok?
 - ♦ speculative
possible
locations for pits,
wumpus
- ♦ Next Action
 - ♦ move
 - ♦ turn left (60
degrees)
 - ♦ turn right (60
degrees)
 - ♦ shoot
 - ♦ grab
 - ♦ exit

© 2004-10 Franz Kurtesz

Lab Exercise Reasoning

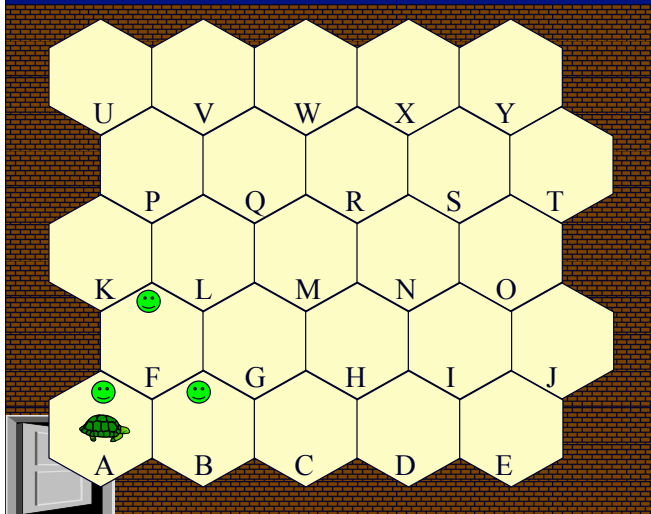
Exploration Example

- ♦ The following slides illustrate the first few exploration steps of the agent.

© 2004-10 Franz Kurtesz

Lab Exercise Reasoning

Hex WW B: Exploration A

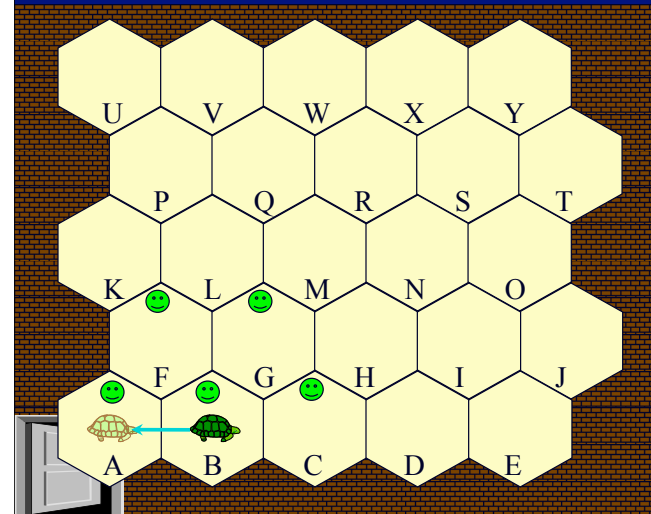


- ♦ Agent Position
A
- ♦ Percept
[_ _ _ _ _]
- ♦ New Knowledge
 - ♦ observation
 - A safe*
 - ♦ reasoning
 - B, F safe*
 - ♦ speculative
- ♦ Next Action
move

© 2004-10 Franz Kurfess

Lab Exercise Reasoning

Hex WW B: Exploration B

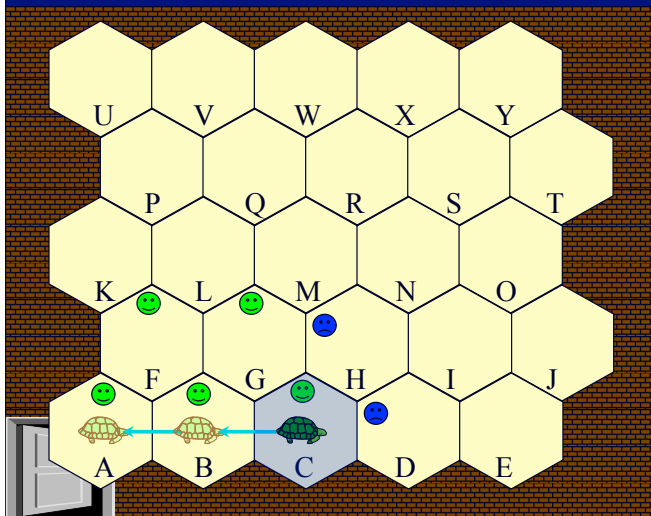


- ♦ Agent Position
B
- ♦ Percept
[_ _ _ _ _]
- ♦ New Knowledge
 - ♦ observation
 - B safe*
 - ♦ reasoning
 - C, G safe*
 - ♦ speculative
- ♦ Next Action
move

© 2004-10 Franz Kurfess

Lab Exercise Reasoning

Hex WW B: Exploration C



- ♦ Agent Position
C
 - ♦ Percept
[_ B _ _ _]
 - ♦ New Knowledge
 - ♦ observation
 - C safe*
 - ♦ reasoning
 - ♦ speculative
 - D, H pit?*
 - ♦ Next Action
turn, (move), turn, (move), turn, turn, move
- (Note: Bumps skipped)

© 2004-10 Franz Kurfess

Lab Exercise Reasoning



© 2004-10 Franz Kurfess

Lab Exercise Reasoning