Real Time Stereo Vision for Robots
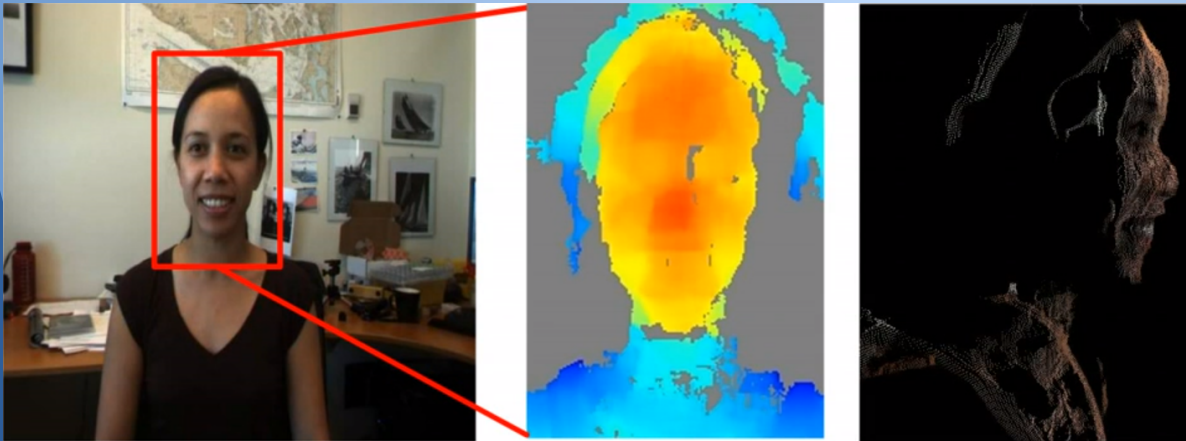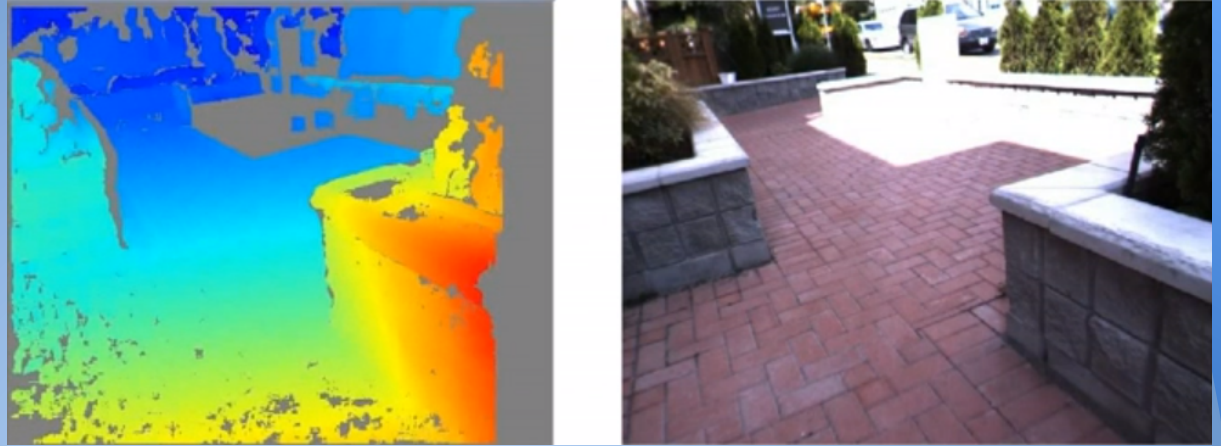
Connor Citron

Depth Map

Point Cloud

Robot needs to detect color and distance

Very Expensive