POINT BASED COLOR BLEEDING WITH CUDA AND CACHING

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Outline

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Introduction

Reasons for Project:

- Global Illumination gives up high quality and realistic images.
- Global Illumination is a lot of work and can always go fast.



Introduction

Project central goals:

- Implementing a Point Based Color Bleeding global illumination algorithm.
- To speed up with CUDA
- To speed up with Caching

 An Octree is a tree structure where every node subdivides space into eight equal pieces.



Octrees are useful because decrease the total amount of work that is required.



- Rasterization: process of converting geometry into pixels.
- Depth-buffer test: the method of saving the distance between image or rasterization buffer and the geometry.



Raytracing



Related Work

 Point Based Color Bleeding by Per H. Christianson.

- Two Central Steps:
 - Surfel Generation
 - Rasterization





Related Work

- Surfel Generation
 - Christianson uses a REYES based approach to generate surfels. This means that each object in the scene is broken down individually and covered with surfels
 - For every Surfel direct illumination is calculated and then surfel is stored into an octree.

Related Work

Rasterization

- For every point that needs to calculate global illumination a raster-cube is generated.
- Surfels are the rasterized onto the faces of the cube.
- Using this information global illumination is calculated.



Current Implementaion

• What I did this quarter:

- Complete C-Style Ray Tracer
 - Direct Illumination
 - Ray-Object Intersections
- Surfel Generation
- CPU Octree
- CPU Surfel Raytracing
- GPU Octree
- GPU Surfel Raytracing

Unrealistic Surfels



Ray Traced Surfels



Surfel Generation

Oifferent from Christianson:

- Ray Casting method
 - Enlarge View Frustum



CUDA Octree

- Normal Octrees do not work with CUDA.
- Adapt Octree to use a array structure.
- This style of Octree took 30 sec of run time



Result Times

2000x2000 Image

- CPU Non-Octree implementation:
 - The world may never know...
- OPU Pointer-Octree: 5 min 15 secs
- OCPU Array-Octree: 4 min 40 secs
- CUDA non-Octree:
 - Had problems: 10 min 43 secs
- CUDA Array-Octree: 13 secs

Future Work

- Rasterization Step
- Spherical Hermonics Calculations
- Octree for Ray-Object Intersections
- CUDA for Ray-Object Intersections
- CUDA Optimizations for Surfel drawings
- Implementation on the new Kepler Nvidia Hardware

Questions?

